

FECBench: A Holistic Interference-aware Approach for Application Performance Modeling

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Abstract—Services hosted in multi-tenant cloud platforms often encounter performance interference due to contention for non-partitionable resources, which in turn causes unpredictable behavior and degradation in application performance. To grapple with these problems and to define effective resource management solutions for their services, providers often must expend significant efforts and incur prohibitive costs in developing performance models of their services under a variety of interference scenarios on different hardware. This is a hard problem due to the wide range of possible co-located services and their workloads, and the growing heterogeneity in the runtime platforms including the use of fog and edge-based resources, not to mention the accidental complexities in performing application profiling under a variety of scenarios. To address these challenges, we present FECBench (Fog/Edge/Cloud Benchmarking), an open source framework comprising a set of 106 applications covering a wide range of application classes to guide providers in building performance interference prediction models for their services without incurring undue costs and efforts. Through the design of FECBench, we make the following contributions. First, we develop a technique to build resource stressors that can stress multiple system resources all at once in a controlled manner, which helps to gain insights into the impact of interference on an application’s performance. Second, to overcome the need for exhaustive application profiling, FECBench intelligently uses the design of experiments (DoE) approach to enable users to build surrogate performance models of their services. Third, FECBench maintains an extensible knowledge base of application combinations that create resource stresses across the multi-dimensional resource design space. Empirical results using real-world scenarios to validate the efficacy of FECBench show that the predicted application performance has a median error of only 7.6% across all test cases, with 5.4% in the best case and 13.5% in the worst case.

Index Terms—Multi-tenant clouds, Performance Interference, Resource Management, Benchmarking.

I. INTRODUCTION

Context: Multi-tenancy has become the hallmark of public cloud computing systems, where physical resources such as CPU, storage and networks are virtualized and shared among multiple different and co-located applications (i.e., tenants) to better utilize the physical resources. Although virtualization technologies such as virtual machines and containers allow cloud providers to increase the degree of multi-tenancy while still providing isolation of resources among the tenants, there exist non-partitionable physical resources such as the caches,

TLBs, disk, and network I/O, which are susceptible to resource contention thereby causing adverse performance interference effects on the co-located tenants [1], [2]. Consequently, effective resource management solutions are required that can limit the impact of performance interference to acceptable levels such that the service level objectives (SLOs) of the applications can be maintained [3], [4], [5], [6].

Challenges: Developing effective resource management solutions (e.g., schedulers) requires an accurate understanding of the target application’s performance under different application co-location scenarios so that the impact of performance interference can be calibrated and accounted for in the solutions. Recent studies [7], [8] have built performance interference profiles for applications using a variety of resource utilization metrics. Since performance interference is caused due to the sharing of one or more non-partitionable resources, performance models for the application-under-study (i.e., the target application) that account for interference are developed by co-locating them with a variety of *resource stressor applications* (i.e., those applications that put varying levels of pressure on the non-partitionable resources) and recording the delivered performance to the target application.

Creating such performance models, however, requires the developer to expend significant efforts into application benchmarking and analyze application performance under varying levels of resource stress. Since the overall system utilization is a function of the stresses imposed on multiple types of resources in the system and the presence of multiple resources represents a multi-dimensional space, creating varying levels of resource stresses spanning this large design space is a difficult task. Effective resource management solutions, however, require application performance models that incorporate the impact of stresses on multiple resources all at once. Although existing resource stressors, such as *dummyload* or *stress-ng* [9], provide users with the control knobs to exert the desired level of stress on a resource, such as CPU or memory, these tools operate on only one resource at a time. Unfortunately, it is hard for users to define the right kinds of application workloads that will create the right levels of resource stress across the multi-dimensional space. All these problems are further exacerbated with the addition of fog and edge computing resources, which illustrate both increased heterogeneity and constraints on resources, and where the performance

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interference effects may be even more pronounced [10], [11].

Although, some frameworks/benchmarks exist that can assist in the building of the performance models, these tools remain mostly disparate and it takes a monumental effort on the part of the user to bring these disparate tools together into a single framework [12]. Even then, such a combined framework may not be easy to use. Moreover, a general lack of any systematic approach to conduct the performance modeling process will force the user to rely on *ad hoc* approaches, which hurts reproducibility and leads to reinvention of efforts [13], not to mention the possibility of the resulting models missing out on critical insights.

Beyond these challenges, one question still persists: *When is a performance model considered good enough such that it will enable effective resource management solutions?* In other words, how much application profiling is required to build these performance models? One strawman strategy to profile the application is to subject it to all possible resource stresses. However, such an approach will be time-consuming and even infeasible given the large number of combinations that can be executed on the different resource dimensions, the variety in the co-located application types, and their different possible workloads. Hence, there is a need for an intelligent application profiling strategy that minimizes the profiling effort and thereby the time and cost, while still providing sufficient coverage across all the resources that contribute to application performance interference. Unfortunately, there is a general lack of benchmarks and frameworks that can aid the user in developing these models.

Solution Approach: To address these challenges, we present FECBench (Fog/Edge/Cloud Benchmarking), an open source framework comprising a set of 106 applications that cover a wide range of application classes to guide providers in building performance models for their services without incurring undue costs and efforts. The framework can then be used to predict interference levels and make effective resource management decisions. Specifically, through the design of FECBench, we make the following contributions:

- 1) FECBench builds resource stressors that can stress multiple system resources all at once in a controlled manner. These resource stressors help in understanding the impact of interference effects on an application’s performance.
- 2) To overcome the need for exhaustive application profiling, FECBench intelligently uses the design of experiments (DoE) approach to enable developers in building surrogate performance models of their services.
- 3) FECBench maintains an extensible knowledge base of application combinations that create resource stresses across the multi-dimensional resources design space.

Empirical results using real-world scenarios for validating the efficacy of FECBench show that the predicted application performance has a median error of only 7.6% across all test cases, with 5.4% in the best case and 13.5% in the worst case. A short poster version of this paper describing initial work can be found in [14].

Paper Organization: The rest of the paper is organized as follows: Section II delves into the details of performance interference, and surveys the literature in this realm; Section III elicits the key requirements for a solution such as FECBench; Section IV presents the design and implementation of FECBench, explaining how it meets the requirements outlined earlier; Section VI-E presents an extensive set of results validating the different features of FECBench; and finally Section VII presents concluding remarks discussing the implications of using FECBench and alluding to future work.

II. BACKGROUND AND LITERATURE SURVEY

In this section we provide details on performance interference and its impact on application performance. We then present a survey of the literature in this area and the limitations of existing approaches, which motivate the key requirements of our FECBench solution.

A. Sources of Interference and Impact on Performance

Co-located applications on the same physical resources of a cloud platform will impose varying degrees of pressure (stress) on the underlying resources. When these resources are hard to partition or isolate, the contention for these resources will cause interference effects on the executing applications and degrade their performance. For compute-intensive applications, resources such as CPU core and Last Level Cache (LLC) can cause interference. Similarly, for communication-intensive applications, resources such as memory bandwidth, disk I/O, and network can cause interference. For example, Figure 1 shows the performance degradation of an application that uses the Inception RESNETv2 deep learning model [15]. The figure illustrates a cumulative distribution function (CDF) for the 95th percentile response times of the application as its SLO with and without interference. Due to the significant difference in the observed response times, it is important for resource management solutions to incorporate the impact of interference to maintain application SLOs.

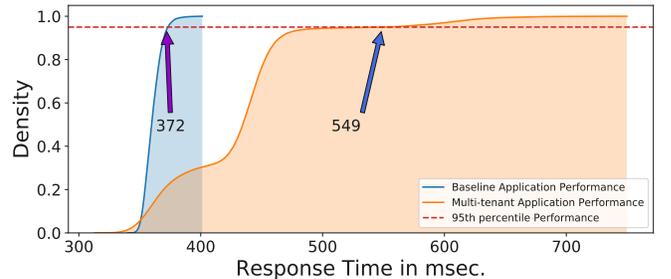


Fig. 1. CDF representation of prediction inference response times for the Inception RESNETv2 Keras model. We can see that the application’s performance degrades when co-located with background applications as compared to its performance when running in isolation.

B. Related Work

We now present prior efforts that focus on quantifying and modeling performance interference and classify these along three dimensions.

Interference Quantification: Two fundamentally different approaches to quantifying performance interference have been reported in the literature. The *Bubble-Up* approach [16] measures *sensitivity* (i.e., impact of co-located applications on the target application) and *pressure* (i.e., impact of the target application on co-located applications) using a synthetic stressor application called *bubble*. The bubble generates a tunable amount of pressure on a given resource, such as memory or LLC. With the pressure applied on a resource, the target application is executed simultaneously with co-located applications, and its performance metrics such as the completion time are measured. This experiment is repeated for different pressure levels in both the memory and the cache subsystems. Although this approach is effective, the bubble is limited to memory sub-system only and the approach is limited to two co-located applications. Yang et. al. [17] extended Bubble-Up to allow performance interference beyond two co-located applications and other shared resources such as network, I/O, cores, etc. The observed application performance degradation is used to construct sensitivity and pressure profiles which are used to determine if a given co-location will cause degradation in the performance of an application.

A different approach is presented in *DeepDive* [8], in which the performance interference is predicted based on the aggregate resource system utilization on the running system. Unlike Bubble-Up, where performance of an application is measured for stress levels independently on each resource, in DeepDive, application interference is measured by monitoring resource usage statistics of all co-located applications. In DeepDive, an application running inside a virtual machine is placed on an isolated physical machine and the resource utilization statistics are measured. The application is then migrated/placed on a physical machine by estimating the quality of interference level on the application and the co-located running applications. Inspired by the approach employed in DeepDive, FECBench leverages system resource metrics to build performance models for applications.

Interference-aware Predictive Modeling: Building performance interference models and using them to predict the expected levels of interference for a given co-location configuration and workloads is important. Paragon [3] presents an interference-aware job scheduler in which an application's performance is predicted using collaborative filtering. The performance prediction model is built using performance data that is measured by subjecting the test application against individual resource stressors that stress only one resource at a time. In comparison, FECBench takes into account the cumulative effect of all the resources to build an interference prediction model.

Zhao et. al. [18] studied the impact of co-located application performance for a single multi-core machine. They developed a piecewise regression model based on cache contention and bandwidth consumption of co-located applications. Similarly, their work captures the aggregate resource utilization of two subsystems, namely, cache contention and memory bandwidth, in determining the performance degradation. Our approach

also considers disk and CPU resources in building prediction models and is not restricted to any hardware.

In DIAL [19], interference detection is accomplished using decision tree-based classifier to find the dominant source of resource contention. To quantify the resource interference impact on a webserver application's tail response, a queuing model is utilized to determine the application's response time under contention. To minimize the effects of interference, it proposed using a runtime controller responsible for dynamic load-balancing of queries from the webserver. Subramanian et. al. [20] presented an application slowdown model which estimates the application performance with high accuracy using cache access rate and memory bandwidth. However, the system was validated using a simulator and not on real hardware. In contrast, FECBench is geared towards real hardware.

The ESP project [21] uses a two-stage process for interference prediction. It first performs feature extraction, and then builds a regression model to predict performance interference. It creates separate models for each co-location groups. Also, its training data workload consists of all the possible applications that can run in the cluster. It then collects performance data for some combinations out of all the possible combinations to build the interference model. Similarly, Pythia [7] describes an approach for predicting resource contention given a set of co-located workloads. Both ESP and Pythia assume that they have *a priori* information of all possible running workloads based on which an interference model is created for a new application. In comparison, FECBench relies on the performance metrics obtained when co-located with a fixed number of resource stressors and does not need to have prior information of all the running applications in the cluster.

Interference-related Synthetic Benchmarks: One of the major roadblocks when investigating and building the performance interference modeling is the lack of representative benchmarking applications. Cuanta [22] built a synthetic cache loader that emulates pressure for varying tunable intensities on the LLC resource. It supports a Linux kernel module that invokes hypervisor system call to create the desired level of memory utilization. This kernel module resides inside a virtual machine. In contrast, our approach is non-intrusive and does not require any changes to the Linux kernel.

iBench [23] developed an extensive set of synthetic workloads that induce pressure on different resource subsystems. These workloads are built in a way to exert tunable utilization pressure on system resources such as L1, L2, iTLB, memory, LLC, disk, network, etc. in isolation. In [24], synthetic workloads were used to create pressure on network and CPU systems. Bubble-up [16], which was described earlier, is another effort in this category.

While these efforts made a step in the right direction, most existing approaches rely on manual tuning of the resource stressors to create the desired level of stress. As a result, prior approaches cannot adapt to changes in the underlying architecture. In contrast to earlier works, our approach finds application pairs and creates a resource stressor knowledge-base in an automated fashion. As a result, our approach can

adapt to changes in the underlying architecture and can be reused. Moreover, with the help of design of experiments, FECBench reduces the profiling effort for the applications.

III. SOLUTION REQUIREMENTS AND PROPOSED APPROACH

Based on the literature survey and unresolved challenges, we derive the following requirements for FECBench.

1. Benchmarking with Ease: Benchmarking and profiling applications can be a very tedious task because it involves configuration of probes on resources such as CPU, network or disk, and collection of many hardware- and application-specific performance metrics [12], [25], [26]. In this regard, tools such as *CollectD* [27] and *Systat* allow monitoring and collecting system metrics. Often, more than one tool may be required to collect the metrics of interest, which makes it hard for the user to integrate the tools. Moreover, dissemination of the monitored metrics in a timely manner to a centralized or distributed set of analysis engines must be supported to build performance interference models of the applications.

To address these challenges and to make the task of benchmarking easier and intuitive for the user, FECBench uses higher-level, intuitive abstractions in the form of domain-specific modeling [28], [29] and generative techniques to synthesize the generation of configurations, metrics collection and dissemination. Our recent work [30] describes these capabilities and hence it is not a focus of this paper but we discuss this requirement for completeness sake.

2. Automated Construction of Resource Stressors: Tools like *lookbusy* and *stress-ng* can be utilized to create resource stress on CPU in a controlled tunable manner. Similarly, tools like *iPerf* can be utilized to create resource stress on the network resource. Despite this, there is a lack of open-source tools that can stress multiple resources simultaneously, also in a tunable manner. Moreover, some of the resource stressors are platform-specific, which hinders their applicability to heterogeneous platforms. Prior studies have presented design of stressors, which requires a deep understanding of the underlying hardware architecture and low-level resource characteristics. Acquiring the skills to utilize these tools thus incurs a steep learning curve.

To address these concerns, Section IV A-G presents a process pipeline with offline and online stages that construct the multi-resource stressors in an automated fashion by leveraging machine learning techniques.

3. Minimizing the Prohibitive Profiling Cost: When building a performance interference model the user must profile the application’s performance metrics against different configurations of resource utilization on the running system. However, since we have multiple resources, the resource utilization can be seen as a multi-dimensional design space. One approach to profiling is to exhaustively cover the entire design space and obtain the performance metrics for the application. However, the cost and time for executing these experiments will be very

high. Thus, there is a need to significantly reduce the profiling effort while deriving good performance interference models.

To that end, we use the *design of experiments* (DoE) approach in Section IV-F to explore the multi-dimensional resource metrics for building the performance interference models. DoE is a statistical technique which has been used to substantially lower the number of experimental runs required to collect data. In our study, we leverage the Latin Hypercube Sampling (LHS) DoE technique.

IV. FECBENCH METHODOLOGY

We now present FECBench and demonstrate its design methodology by building a performance interference model and explaining each step of its design.

A. FECBench Methodology and its Rationale

Figure 2 presents the FECBench process. The rationale for this process is described below and details of each step follow.

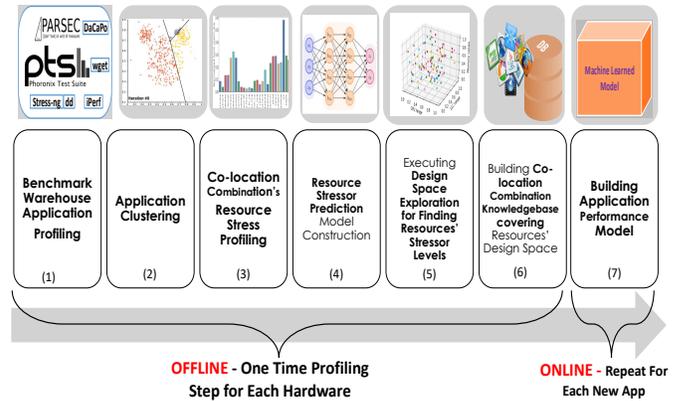


Fig. 2. FECBench methodology.

Recall that the goal of FECBench is to minimize the efforts for developers in building interference-aware performance models for their applications by providing them a reusable and extensible knowledge base. To that end, FECBench comprises an offline stage with a set of steps to create a knowledge base followed by an online stage. Developers can use the same offline stage process to further refine this knowledge base.

Accordingly, the first step (in §IV-B) of the offline stage defines *Benchmark Warehouse* (BMW), which is a collection of resource utilization metrics obtained by executing a large number and variety of applications on a specific hardware and measuring the impact on each resource type independently. The second step (in §IV-C) clusters these applications according to their similarity in how they stress individual resources. Clustering minimizes the unwieldiness stemming from the presence of a large number of application types in the performance model building process. Next since we are interested in performance interference, the knowledge base must capture the stress on resources stemming from executing a combination of co-location patterns of applications belonging to the different clusters found in the earlier step (Step 3 in §IV-D).

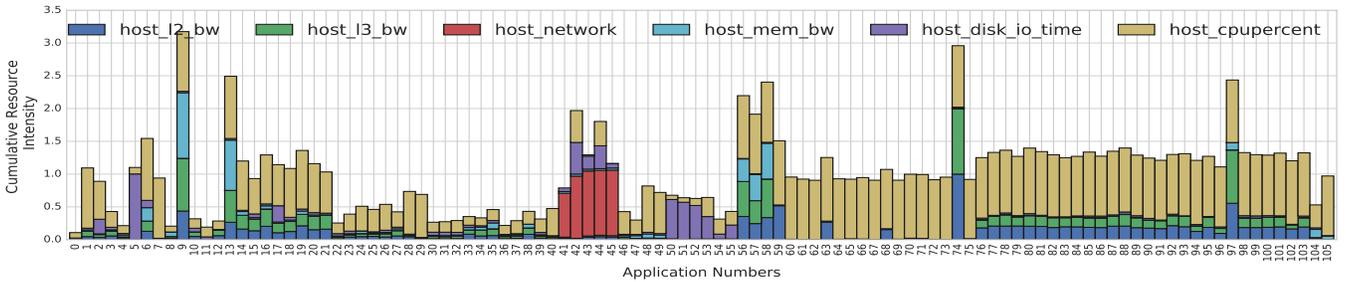


Fig. 3. Utilizations of different resources for each of the 106 applications from the benchmarking warehouse. Each application is represented by a unique number and is depicted along the horizontal axis.

Using all this data, we define a resource stressor prediction model (Step 4 in §IV-E), which can be used to predict the expected stress along the multi-dimensional resource space given a new co-location pattern. Since such a model building process itself may need exhaustive searching through every possible combination of resource stresses along the multi-dimensional resource space, we create surrogate models using design of experiments (DoE), specifically, the Latin Hypercube Sampling (LHS) approach (Step 5 in §IV-F).

The reduced search strategies of Step 5 give rise to a knowledge base (Step 6 in §IV-G), which is then used in the online stage (Step 7 in §IV-H) that stresses a target application across different resource utilization regions from the design space to train a model for that target application and utilize it to predict its performance at runtime. The developer of a new application need only conduct Step 7 while leveraging all the previous steps. If a completely new hardware configuration is presented, the knowledge base must be updated by repeating all the steps of the offline stage. The steps are detailed next.

B. Benchmarking Isolated Characteristics of Applications

To build stressors that can stress different resources of a system, we first study the characteristics of different applications in isolation. We have profiled 106 applications from existing but disparate benchmarking suites, such as PARSEC [31], DaCaPo [32], PHORONIX [33], STRESS-NG [9], as well as networked file-server applications, which collectively form our *benchmarking warehouse* (BMW). These applications represent a diverse range spanning from cloud computing to approximate computing workloads [34].

In this step, we profile the applications by running them in isolation on a system so as to document the resource utilization imposed by that application. Let A denote the set of all applications in BMW. For each application $a \in A$, we collect its runtime utilization metrics on the host system when run in isolation, including CPU, L2/L3 cache bandwidth, memory bandwidth, disk, network, etc. For a total number R of resources considered, the vector $U(a) = [u^{(1)}(a), u^{(2)}(a), \dots, u^{(R)}(a)]$ is then logged in a database, where $u^{(r)}(a)$ denotes the utilization on a particular resource $r \in \{1, 2, \dots, R\}$ when running the application. Figure 3 presents the resource utilization characteristics of 106 applications. The experiment host used is Intel(R) Xeon(R) CPU E5-2620 v4 machine with 16 physical

cores. As we can see from the figure, the applications exhibit a high degree of coverage across the resource utilization spectrum for the different system resources.

C. Application Clustering

Given the large number of applications available in the BMW, it is likely that some of them exhibit similar characteristics with respect to the resource utilizations. For example, applications with numbers 80 and 81 in Figure 3 have similar utilizations with respect to CPU, L2 bandwidth and L3 bandwidth. This step performs clustering to identify those applications that share similar resource utilization characteristics. Moreover, application clustering allows us to select only a subset of applications from the BMW for the subsequent co-location resource utilization study. This helps to significantly reduce the number of application combinations that need to be profiled and tested.

Machine learning approaches, such as K -means clustering or Support Vector Method-based clustering, have been commonly used to find similarities in datasets [35]. In this study, we leverage the K -means algorithm to cluster all applications from the BMW in the R -dimensional space, where each dimension represents the utilization from a particular resource $r \in \{1, 2, \dots, R\}$. Thus, each application $a \in A$ is represented by a point $U(a) = [u^{(1)}(a), u^{(2)}(a), \dots, u^{(R)}(a)]$ in the R -dimensional space. We use the Silhouette algorithm [36] to determine the ideal number of clusters. For the considered 106 applications, running the algorithm leads to $K = 13$ clusters. Figure 4 shows the resource utilization characteristics for some of these clusters. As can be seen, Cluster 5 is L3, L2 and L3-system bandwidth-intensive. Similarly, Cluster 2 is memory bandwidth intensive. Cluster 9 shows high utilization pressures across network, disk and CPU.

D. Resource Utilization Profiling for Co-located Workloads

Since running a single application may not create the desired stress levels for the system resources, we are interested in finding those application mixes that together can create a more diverse set of resource stress levels. We first observe from our empirical experiments that the utilization of a resource on a system by running a set of co-located applications cannot be obtained by simply summing the resource utilizations of these applications when executed in isolation. This is validated by

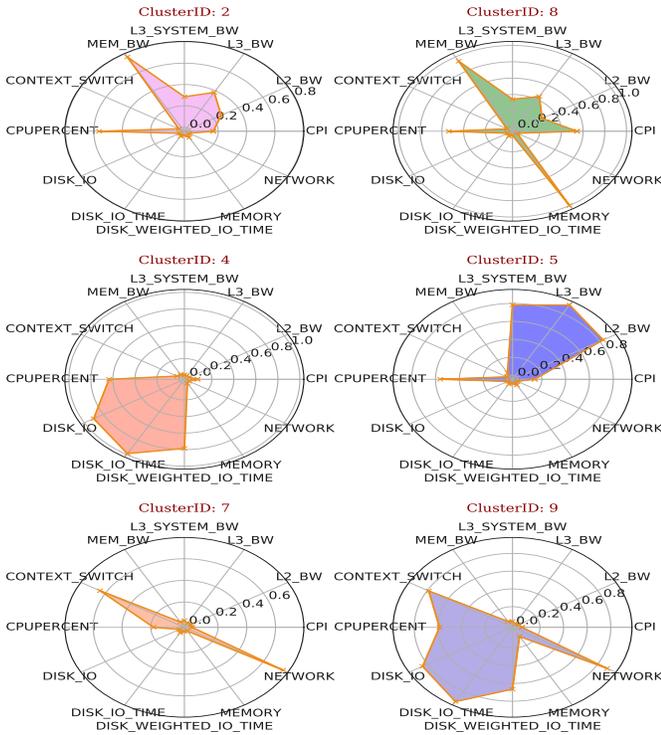


Fig. 4. Radar charts illustrating the resource profiles for clusters 2, 4, 5, 7, 8 and 9. Resource pressure is higher when the vertices are closer to the edge of the radar chart on the resource axis.

Figure 5, which shows that a direct summation of the isolated applications' L3 bandwidth utilizations incurs significant difference margins, with a mean absolute percent error of 47%. Similar behavior is also seen for other system resources.

This calls for profiling the resource utilization characteristics of different application co-location patterns. However, empirically running all application combinations is extremely time consuming. This step and the next together build a resource prediction model that determines the resource utilizations for any given application co-location pattern.

Before building a resource prediction model, we collect resource utilization data in this step by profiling a selection of application mixes, similar to the way we profiled a single application in Section IV-B. Specifically, we pick an arbitrary application (e.g., the centroid) from each of K clusters and co-locate applications from different clusters to create different resource stressors. Let d^{\max} denote the maximum number of co-located applications that are allowed in a run. This gives a total of $\sum_{d=1}^{d^{\max}} \binom{K}{d}$ application combinations.

Depending on the execution time needed to perform the profiling, one can choose a random subset of these combinations for building the prediction model. In our experiment, we have $K = 13$ and $d^{\max} = 8$ (since we are using a 16-core server and each application executes on 2 cores), which gives a total of 7,098 combinations. Among them, we profiled around 2,000 combinations for building the prediction model.

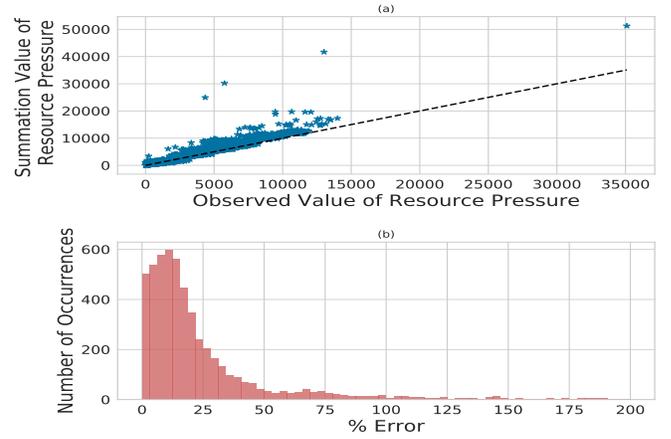


Fig. 5. Chart (a) shows the summation of the isolated L3 bandwidth resource pressures and the observed resource pressure on the system. Chart (b) shows the distribution of error from direct summation of isolated resource pressures of the applications. The mean absolute percentage error is 47%.

E. Building Resource Stressor Prediction Model

Based on the resource utilization data collected from the last step, this step builds a resource stressor prediction model. We leverage random forest regression to determine the individual resource utilization given a set of co-located applications. Random forest regression is a widely used non-parametric regression technique for capturing non-linearity in the dataset. Unlike other methods, it performs well even with a large number of features and a relatively small training dataset, while providing an assessment of variable importance. Random forest is an ensemble-learning-based approach, where the results of multiple models, in this case, decision trees, are averaged to provide the final prediction. A decision tree recursively partitions a sample into increasingly more homogeneous groups up to a pre-defined depth. Terminal nodes in the tree then contain the final result. Random forest randomizes the creation of decision trees in two ways: 1) each decision tree is created from a random subset of input data; 2) each tree-partition is based on a random subset of input features.

For any application combination A , the following input features are used in the random forest prediction model:

- A K -dimensional vector $C = [c_1, c_2, \dots, c_K]$, where each element c_i takes the value 1 if an application from the i -th cluster is selected in the combination A and 0 otherwise.
- A R -dimensional vector $U_+(A) = [u_+^{(1)}(A), u_+^{(2)}(A), \dots, u_+^{(R)}(A)]$, where each element $u_+^{(r)}(A)$ represents the sum of individual utilizations for the r -th resource from all applications in A , i.e., $u_+^{(r)}(A) = \sum_{a \in A} u^{(r)}(a)$.

The output is another R -dimensional vector that predicts the utilization for all resources when executing the application combination A , i.e., $\tilde{U}(A) = [\tilde{u}^{(1)}(A), \tilde{u}^{(2)}(A), \dots, \tilde{u}^{(R)}(A)]$. Thus, the resource stressor prediction model maps the input

to the output via a prediction function f as follows:

$$\tilde{U}(A) \leftarrow f(C, U_+(A))$$

F. Design of Experiments (DoE) Specification

To build a performance interference model for a target application when it is co-located with other applications, we need to measure its performance on a system that experiences different resource stress levels. Due to the large number of possible stress levels along multiple resource dimensions, it is not practical to test all of them. Therefore, we adopt the design of experiments (DoE) [37] approach by generating a small number of sample points in the multi-dimensional space that maximizes the coverage of the different resource utilizations.

To this end, we leverage the Latin Hypercube Sampling (LHS) method [37] that generates sampled regions across the R -dimensional resource utilization space. Specifically, LHS divides each resource dimension into M equally-spaced intervals, and then selects M sample intervals in the entire R -dimensional space that satisfies the Latin Hypercube property: each selected sample is the only one in each axis-aligned hyperplane that contains it. The LHS method has a clear advantage over random sampling, which could potentially lead to selections of samples that are all clumped into a specific region. Moreover, the number M of samples in LHS does not grow with the number of dimensions. For a given choice of M , it generates a collection $H = \{h_1, h_2, \dots, h_M\}$ of M hypercubes. Since each dimension represents the resource utilization of a corresponding resource in our case, its overall range is $[0, 1]$. Therefore, each generated hypercube $h_i \in H$ in a resource dimension r has the range $\left[\frac{x_i^{(r)}}{M}, \frac{x_i^{(r)}+1}{M}\right]$ for some $x_i^{(r)} \in \{0, 1, \dots, M-1\}$. We refer interested readers to [38] for an in-depth explanation of the LHS method. In our experiment, we set $M = 300$.

G. Creating the Stressor Knowledge Base

We now create a knowledge-base of applications and their workload mixes that map to the different resource utilization levels as determined from the DoE exploration. Let \mathcal{SA} denote the set of all application combinations generated in Section IV-D. We consider every application combination $A \in \mathcal{SA}$ and use the resource stressor prediction model of Section IV-E to predict its utilization $\tilde{u}^{(r)}(A)$ for each individual resource $r \in \{1, 2, \dots, R\}$. We then fill up each of the M hypercubes sampled in Section IV-F with the application combinations that belong to it. Specifically, for each application combination A , it is assigned to hypercube $h_i \in H$, if $\tilde{u}^{(r)}(A) \in \left[\frac{x_i^{(r)}-\delta}{M}, \frac{x_i^{(r)}+1+\delta}{M}\right]$ for all $1 \leq r \leq R$, where $\delta > 0$ is a tolerance parameter to extend the boundaries of the hypercubes to account for the inaccuracy of the stressor prediction model. In our experiment, we set $\delta = 0.1$.

H. Building Performance Interference Prediction Model

In the last step (which is an online step), a developer must construct a performance interference prediction model for a

new target application b that is introduced for the first time onto the platform. The goal is to predict a specified QoS metric q for the target application when it is co-located with any set B of applications. To that end, we leverage a regression-based Decision Tree model [39]. The input of the prediction model is a R -dimensional vector $U = [u^{(1)}, u^{(2)}, \dots, u^{(R)}]$ showing the utilization of different system resources before the target application b is deployed. The output is the predicted QoS metric for the target application b , which we denote as $\tilde{q}(b, U)$, under the current system utilization U . Thus, the interference prediction model maps the input to the output via a prediction function g as follows:

$$\tilde{q}(b, U) \leftarrow g(U)$$

To build the regression model, the target application is executed under different resource stress levels identified by the design of experiments in Section IV-F. For each of the M resource stress levels, the target application is executed along with a selected application combination from the knowledge base that corresponds to the desired resource stress level. To select the application combination, the closest application to the center of each hypercube is chosen. This selected application combination is first run on the platform. After a warm-up period, the target application is then deployed on the same platform, and its performance QoS metric is logged. This process is repeated for all the M resource stress levels. The results are used as training data to train the regression model above. In FECBench, we consider the response time, which is the computation time of the application, as the QoS metric used for latency-sensitive applications with soft real-time requirements.

V. SYSTEM ARCHITECTURE AND IMPLEMENTATION

Figure 6 shows the different components of FECBench. There are two classes of nodes: *manager host* and *physical hosts*. Manager host is responsible for the management and orchestration of FECBench. We describe the numbered components in the figure below.

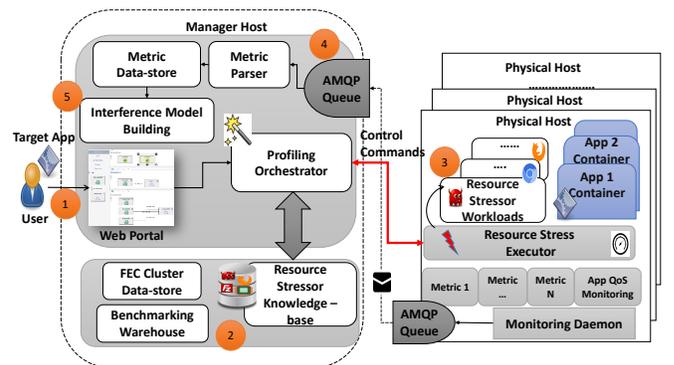


Fig. 6. FECBench in action. The figure shows different components of the FECBench along with the manager host and the target physical hosts on which application profiling takes place.

In ①, the *Webportal* component at the manager host allows the user to interact with FECBench. The Webportal

is built using a visual domain specific modeling language [40]. It allows the user to submit the target application whose performance interference model needs to be constructed. The Webportal initiates the profiling of the target application, and relays this information to the *Profiling orchestrator*, which then fetches the required information – resource stressors and system availability – from the FECBench system information block represented by ②. Components in ② comprise the FEC Cluster datastore, Resource Stressor Knowledgebase, and Benchmarking Warehouse. The FEC Cluster datastore consists of the current information about the cluster. Equipped with the required information, the Profiling orchestrator deploys the target application on the desired physical host, where the interference-aware profiling of the application takes place. In ③, the target application is subjected to various resource stressors as obtained from the stressor knowledge base. The monitoring probes on the physical hosts monitor the system as well as the application QoS metrics and this information is relayed to the manager host. In ④, the desired metrics are parsed and data is stored in a time series datastore. In ⑤, FECBench constructs the interference-aware performance model of the target application.

The monitoring of the system performance metrics is done using the *CollectD* monitoring program. For the system metrics not supported by CollectD, custom Python based plugins are written that feed the metric data to the CollectD daemon. CollectD plugins for the Linux *perf* utility and *Likwid* monitoring tool [41] are written to monitor and log additional system metrics such as the cache-level and memory-level bandwidth information. Docker-based resource stressor containers have also been built. The monitored metrics are relayed in real time using AMQP message queues. Metric parsers for the gathered data are written using both Golang and Python languages. We use *Influxdb* to provide a time series database for storing the monitoring metrics [42]. For building performance models, we leverage the machine learning libraries provided by the *Scikit* library in Python [43].

VI. EXPERIMENTAL VALIDATION

This section validates the claims we made about FECBench. To that end, we demonstrate how FECBench enables savings in efforts in building the performance models of applications and their accuracy in making resource management decisions. We validate the individual steps of the FECBench process. We also present a concrete use case that leverages FECBench for interference-aware load balancing of topics on a publish-process-subscribe system.

A. Experimental Setup

We validated the FECBench claims for a specific hardware comprising an Intel(R) Xeon(R) CPU E5-2620 v4 compute node with 2.10 GHz CPU speed, 16 physical cores, and 32 GB memory. The software details are as follows: Ubuntu 16.04.3 64-bit, Collectd (v5.8.0.357.gd77088d), Linux Perf (v4.10.17) and Likwid Perf (v4.3.0). For the experiments, we configured

the `scaling_governor` parameter of CPU frequency to performance mode to achieve the maximum performance.

B. Validating the Resource Stressor Prediction Model

To build and validate the resource stressor prediction model (Step 4 of FECBench), we first need to obtain a dataset that includes the resource utilizations under different application co-location scenarios (Step 3). In our experiment, we pin each application to 2 cores of the test node for a maximum of 8 co-located applications (since the node has 16 cores). Our offline profiling for Step 3 produced a dataset of about 2,000 data points, of which we used 80% for training, 10% for testing and the remaining 10% for validation. Table I illustrates the performance of the resource stressor prediction model. We see that the learned models have high accuracy for both the test and the trained dataset. We used the same accuracy measure, *coefficient of determination* (R^2), as in prior studies [21]. We observe an accuracy of 99.1% and 99.3% for the training and testing data, respectively, for memory bandwidth. The learned model also has low bias and variance since both testing and validation errors converge for most cases.

TABLE I
PERFORMANCE OF LEARNED MODELS FOR RESOURCE STRESSORS

Feature	Test Accuracy	Train Accuracy	Validation Accuracy
MEM_BW	99.305	99.073	98.930
CPUPERCENT	89.896	88.776	88.889
MEMORY	98.310	98.346	86.143
L3_BW	99.085	98.839	98.037
NETWORK	99.663	99.665	99.673
L3_SYSTEM_BW	99.367	98.888	98.452
L2_BW	99.454	99.130	97.916
DISK_IO_TIME	88.002	88.464	88.519

Figure 7 shows the accuracy of FECBench in predicting the actual resource utilizations for the co-located workloads. We see that the resource utilization predicted by FECBench are quite accurate as the bulk of the points fall close to the diagonal region of the chart with very few outliers.

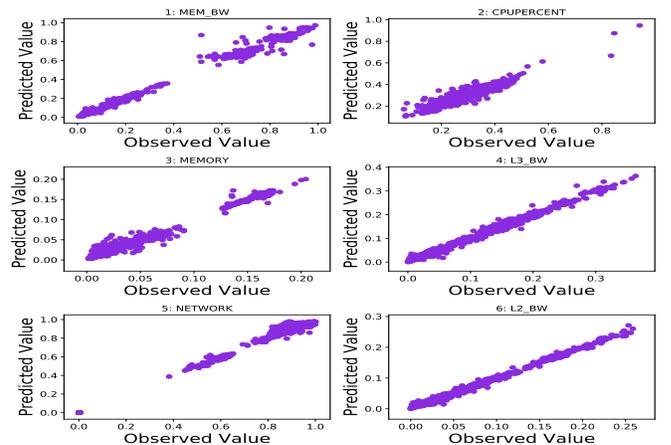


Fig. 7. Predicted resource utilizations across different resource types. Points concentrated along the diagonal indicate that the predicted values match the actual observed values.

C. Validating the Design Space Exploration Strategy

For this experiment, the goal is to find the right application combinations that exert pressure in a tunable fashion along multiple resource dimensions (in our case, CPU, memory bandwidth and disk resources). We set the number of samples for the LHS strategy to 300 in the design of experiments, and got coverage for around 264 bins, i.e., 88%. To allow for easier visualization of the coverage, we project the three dimensional datapoints on a two dimensional scale as shown in Figure 8, demonstrating good coverage of the design space.

D. Validating the Accuracy of the Performance Models

We used specific applications drawn from the DaCaPo benchmark, the Parsec benchmark and the Keras machine learning application model as target applications whose performance models we were interested in. Specifically, from the DaCaPo benchmark, we chose PMD which is an application that analyzes large-scale Java source code classes for source code problems. From the Parsec benchmark, we chose the Canneal application, which uses a cache-aware simulated annealing approach for routing cost minimization in chip design. The Canneal program has a very high bandwidth requirement and also large working sets [31]. From the Keras machine learning application model, we used InceptionResnetV2, which represents an emerging workload class for prediction inference serving systems [15].

We first build performance models for these three applications using our approach as discussed in Section IV. To test the effectiveness of the learned application performance models, we co-locate the target applications with the web search workload from the CloudSuite benchmark [44], which uses the Apache Solr search engine framework and emulates varying number of clients that query this web search engine. We ran four different scenarios with varying number of clients: 600, 800, 900, and 1000. We placed our target application with a co-located web-search server on the host compute node. We assigned two cores to the target application and the rest of the cores to the web-search server.

Figure 9 shows the mean absolute percent errors (MAPEs) for the three applications under varying degrees of loads generated by the clients of the co-located web search application. For example, when the number of clients is 800, the MAPEs are 6.6%, 11.8% and 14.5% for PMD, Canneal and InceptionResnetV2, respectively. Also, the median percentage errors for all the cases are below 5.4%, 7.6% and 13.5% for PMD, Canneal and InceptionResnetV2, respectively. To showcase the total number of correct predictions made by the system, we leverage a CDF curve that has been used in the literature to showcase the effectiveness of the machine learning models [45]. Figure 10 illustrates that, for the PMD application, 80% of the predictions have error rates less than 9%. For the Canneal application, 80% of the predictions have error rates below 15%. For the InceptionResNetV2 application, about 70% of the predictions have error rates below 25%.

E. FECBench in Action: A Concrete Use Case

Besides validating the efficacy of FECBench on applications drawn from the benchmarking suites, we have applied FECBench to interference-aware load balancing of topics for a publish-process-subscribe system [46]. The Publish/Subscribe (pub/sub) communication pattern allows asynchronous and anonymous exchange of information (topic of interest) between publishers (data producers) and subscribers (data receivers). Therefore, pub/sub is widely used to meet the scalable data distribution needs of IoT applications, where large amounts of data produced by sensors are distributed and processed by receivers for closed-loop actuation. The need for processing sensor data is accomplished on broker nodes that route information between publishers and subscribers.

In a publish-process-subscribe system, a topic's latency can suffer significantly due to the processing demands of other co-located topics at the same broker. Figure 11 demonstrates this effect. Here, a topic is characterized by its processing interval p , i.e., average time for processing each incoming message on the topic, and cumulative publishing rate r , at which messages arrive at the topic. Figure 11(a) shows that topics A, B and C show wide variations in their 90th percentile latencies (~ 100 ms to ~ 800 ms) under varying background loads.

For latency-critical IoT applications, it is necessary to ensure that a topic's latency is within a desirable QoS value. Therefore, it is important to co-locate topics at the brokers in an interference-aware manner such that none of the topics in the system violate their latency QoS. To this end, one approach is to learn a latency prediction model for the brokers in the pub/sub system by leveraging the FECBench approach. Subsequently, the latency prediction model can be used to determine which topics can be safely co-located at a broker without incurring QoS violations. Figure 11(b) shows how such an interference-aware method can reduce the percentage of topics in the system that suffer from QoS violations. Here, the interference-aware approach, which uses the latency prediction model obtained by the FECBench approach, is able to meet the QoS for $\sim 95\%$ of the topics in the system. This is significantly better than a naive approach based on round robin scheduling, which is only able to meet the QoS for $\sim 80\%$ of the topics in the system.

VII. CONCLUSION

Making effective dynamic resource management decisions to maintain application service level objectives (SLOs) in multi-tenant cloud platforms including the emerging fog/edge environments requires an accurate understanding of the application performance in the presence of different levels of performance interference that an application is likely to encounter when co-located with other workloads. Data-driven performance models can capture these properties, which in turn can be used in a feedback loop to make effective resource management decisions [47]. The vast number of applications, their co-location patterns, differences in their workload types, platform heterogeneity and an overall lack of a systematic performance model building framework make it an extremely

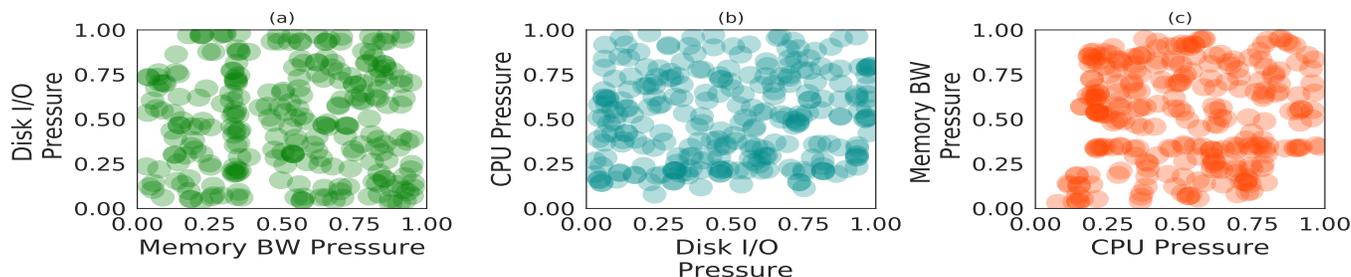


Fig. 8. Coverage of the resource stressor design space exerted by the co-located application combinations available in the knowledge base.

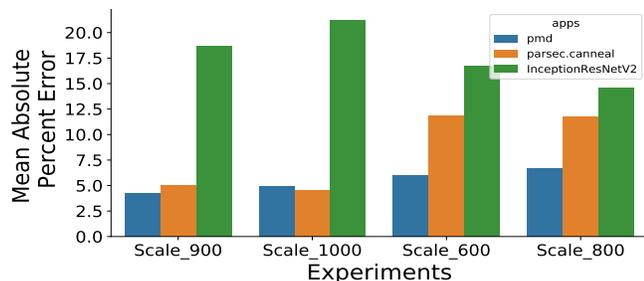


Fig. 9. Prediction accuracy in mean absolute percent error for PMD, Canneal, InceptionResNetV2 applications when co-located with web search server from CloudSuite.

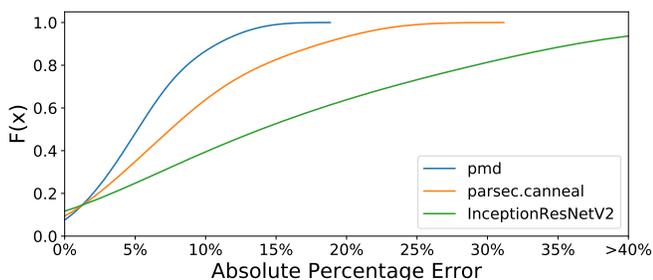


Fig. 10. Cumulative distributions of prediction errors for the PMD, Canneal, InceptionResnetV2 applications.

daunting task for developers to build such performance models. FECBench (Fog/Edge/Cloud Benchmarking) is a framework that addresses these challenges, thereby relieving the developers from expending significant time and effort, and incurring prohibitive costs in this process. It provides an extensible resource monitoring and metrics collection capability, a collection of disparate benchmarks integrated within a single framework, and a systematic and scalable model building process with an extensible knowledge base application combinations that create resource stress across the multi-dimensional resources design space. Empirical evaluations on different application use cases demonstrate that the predicted application performance using the FECBench approach incurs a median error of only 7.6% across all test cases, with 5.4% in the best case and 13.5% in the worst case. FECBench is available in open source at <https://github.com/doc-vu/fecbench-ansible>.

So far, FECBench has been evaluated on a single hardware

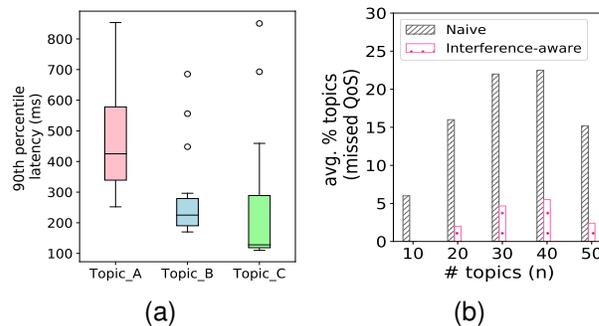


Fig. 11. Use of FECBench in publish-process-subscribe showing: (a) impact of co-location on a topic’s latency; (b) interference-aware placement of topics.

platform. Its efficacy needs to be validated on a variety of hardware platforms. To that end, we will explore the use of transfer learning to minimize the efforts. Our use of 106 applications did not provide coverage across every possible resource dimension and hence improving the coverage is another area of future work.

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